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(54) Title: BRUSHLESS SYNCHRONOUS ELECTRIC MOTOR		
(57) Abstract	<p>A brushless synchronous electric motor comprises a stator (2) which has, viewed in cross-section, along a right-angled cross-sectional plane with respect to the rotor axis, a substantially rectangular shape. The stator has internally a plurality of slots (4) which house a stator electric winding. The slots extend lengthwise in a direction parallel to the axis of the rotor (3) and are distributed circumferentially around the rotor within two arcs of a circumference, each having an amplitude (α) equal to about a whole fraction of the flat angle and being situated on diametrically opposite sides with respect to the rotor axis. The motor is able to achieve a relatively high peak torque in relation to its dimensions.</p>	

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Description

Brushless synchronous electric motor

Technical field

5 The present invention relates to a brushless synchronous electric motor.

In a specific, but not exclusive manner, the present invention may be used, in an automatic machine or a robot system, in order to operate a movable mechanical 10 component such as, for example, a spindle or a manipulator.

In particular, reference is made to a brushless synchronous electric motor comprising a stator and a rotor housed in the centre of the stator; the stator has internally a plurality of slots which house a 15 stator electric winding; the slots extend lengthwise in a direction parallel to the rotor axis and are distributed circumferentially around the rotor.

Background art

20 Motors of the abovementioned type, in which the rotor has peripherally permanent magnets surrounded coaxially by an air gap, are widely known. The latter separates the rotor from a stator magnetic circuit comprising a pack of laminations having, formed in 25 them, the slots housing the stator electric winding.

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In known motors, the slots are distributed uniformly, in a circumferential direction with respect to the rotor, at a constant interval, over a complete circumference of 360°. Generally, the known motors
5 have a stator with a square or circular cross-section. Motors of this type are already used for the operation of movable components of automatic machines or robot systems. Normally, in these cases, it is envisaged that the motor performs variable-speed work cycles
10 with frequent reversals in the direction of rotation of the rotor, the motor being supplied with power by means of an electronic driver. Therefore, the motor must be able to provide high torques and a high mechanical power output in a non-continuous operating
15 condition. For this purpose it is necessary to use motors having relatively large dimensions. Generally, both in order to limit the inertia of the rotating masses, and in order to contain the frontal dimensions (heightwise and widthwise) of the motor, it is
20 preferable to construct motors extending lengthwise in a direction parallel to the rotor axis, rather than motors extending in a direction transverse to the said axis.

One of the drawbacks of the known motors of the type
25 described above consists in the fact that, if the

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maximum power required is high, the motor needed to generate this power must have frontal dimensions, namely in a plane perpendicular to the rotor axis, which are relatively large. However, in certain 5 situations (for example in an automatic machine or a robot system) the space available for mounting the motor may be limited, while the maximum overload power required is high. Consequently, it is not possible to reduce, beyond a certain limit, the dimensions of an 10 automatic machine or a robot system which uses an electric servomotor of the abovementioned type, since the servomotor must in any case have fairly large frontal dimensions, otherwise it will be unable to provide the power required.

15 Disclosure of the invention

The object of the present invention is to overcome the abovementioned drawback of the known art by means of an electric motor having relatively small dimensions in relation to the maximum peak power which can be 20 output.

One advantage of the invention is to provide a motor able to provide a relatively high maximum torque in relation to its volume.

Another advantage of the invention consists in the 25 fact that it is simple and inexpensive to manufacture

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and use.

Brief description of the drawings

Further characteristic features and advantages of the present invention will emerge more clearly from the following detailed description of some preferred, but not exclusive embodiments of the said invention, illustrated purely by way of a non-limiting example in the accompanying drawings in which:

Figure 1 shows a cross-sectional view of a first example of embodiment along a longitudinal plane;

Figure 2 shows a profile or frontal view of the motor according to Figure 1;

Figure 3 shows a diagram of the stator electric winding of the motor according to Figures 1 and 2;

Figure 4 shows a cross-sectional view of a first example of embodiment along a plane perpendicular to the motor axis, indicated by the line V-V;

Figure 5 shows a cross-sectional view of a second example of embodiment along the plane indicated by V-V in Figure 1.

Detailed description of the preferred embodiment(s)

With reference to the abovementioned figures, 1 denotes in its entirety a brushless synchronous electric motor comprising a stator 2 and a rotor 3 housed in the centre of the stator. The motor 1 may

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be advantageously used to operate the moving parts of an automatic machine and/or a robot system.

The stator 2 has internally a plurality of slots 4 which house a stator electric winding 5. The slots 4 extend lengthwise in a direction parallel to the axis x-x of the rotor and are distributed circumferentially around the rotor 3.

The slots 4 are arranged within two arcs of a circumference, each having an amplitude smaller than a flat angle and being situated on diametrically opposite sides with respect to the axis x-x of the rotor. Preferably the amplitude of each of the two arcs of a circumference is equivalent to about a whole fraction of the flat angle. In the case of Figure 4, the mechanical (i.e. geometrical) amplitude α of each arc is 60° . In the case of Figure 5, which will be described in more detail below, this amplitude α is equal to 90° . In another example, not shown, the amplitude α may be 45° .

The stator 2 has, viewed in cross-section, along a right-angled cross-sectional plane with respect to the axis x-x of the rotor (see Figure 1), one dimension which is substantially smaller than the other one. In particular, the stator 2 has a substantially rectangular shape, viewed in cross-section (see Figure

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2). The short side of the rectangular section of the stator has a length slightly greater than the external diameter of an air gap 6 separating the rotor 3 and the stator 2.

5 The arcs of a circumference inside which the slots 4 are arranged are situated on opposite sides with respect to a longitudinal plane A-A passing through the axis x-x of the rotor and parallel to the smaller dimension of the stator 2. The thickness of the
10 stator, considered in a radial direction with respect to the axis x-x of the rotor, is minimal in two zones of the stator located in the vicinity of the abovementioned longitudinal plane A-A, as can be seen from Figures 2, 4 and 5. These parts of the stator 2
15 face the air gap 6 separating the rotor and the stator. These parts have a very small thickness which may be, if necessary, the minimum thickness necessary for ensuring continuity of the magnetic circuit of the stator 2.

20 The stator 2 comprises a pack of rectangular laminations, having twelve slots distributed over two facing arcs, i.e. six slots for each arc. Each arc has an angular amplitude of 60° and is diametrically opposite, with respect to the rotor axis, to the other
25 arc of slots. The slots in the lamination are

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designed to receive the three-phase winding 5 schematically shown in Figure 3. The winding 5 has voltages which are phase-displaced by 120° with respect to each other. Each phase of the stator 5 winding is associated with four slots, with two slots for each phase pole.

The rotor is constructed so as to form six magnetic poles. It is possible to drive the motor with brushless operation of the known type, using Hall 10 sensors positioned in accordance with the structure of a brushless motor with six poles of the known type.

The motor 1 has a small width, although being able to provide a relatively high peak power. In particular, it has been found that the motor 1 is able to achieve 15 peak torques nearly the same as those of an electric motor of the known type with six stator poles and six rotor poles, having substantially the same rotor diameter and the same heightwise and lengthwise dimensions as the motor described above, but with 20 larger dimensions widthwise owing to the fact that the slots for housing the stator are distributed over 360° around the rotor axis. Comparing the motor according to Figures 1 to 3 with the known motor described above, the continuous power output by the former is 25 about one third that output by the latter, while the

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peak power in an overload condition which may be output by the first motor is practically the same as or in any case slightly smaller than that which may be output by the second motor; this is apparently due to
5 the fact that the rotor diameter is the same in both cases. In applications where it is required to have a high non-continuous peak power output rather than a high continuous power output (for example in order to operate the moving parts of an automatic machine or a
10 robot system), the first motor offers the advantage of having frontal dimensions which are decidedly smaller. In the example according to Figure 5 the same numbers as in Figure 4 have been used to indicate similar parts. The rotor 3 has eight magnetic poles. The
15 stator lamination pack has twelve slots 4 distributed in two groups of six situated opposite with respect to the axis x-x of the rotor 3. Each group of slots is arranged around the rotor 3 with an arc of a circumference having an amplitude α equal to 90°..
20 With the motor 1 according to Figure 5, it is possible to obtain about half the continuous power, but peak torques nearly the same as those of an electric motor of the known type with eight stator poles and eight rotor poles, having the same rotor diameter and slots
25 for housing the stator electric circuit distributed

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around 360°. In this case also, the widthwise dimensions of the motor in question are smaller than those of the motor of the known type able to output the same peak power.

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Claims

1. Brushless synchronous electric motor comprising a stator (2) and rotor (3) housed in the centre of the stator, the stator having internally a plurality of slots (4) which house a stator electric winding (5), the slots extending lengthwise in a direction parallel to the axis (x-x) of the rotor and being distributed circumferentially around the rotor (3), characterized in that the slots (4) are arranged within two arcs of a circumference, each having an amplitude (α) smaller than a flat angle and being situated on diametrically opposite sides with respect to the axis (x-x) of the rotor.
2. Motor according to Claim 1, characterized in that the amplitude (α) of each of the two arcs of a circumference is equal to about a whole fraction of the flat angle, preferably $180^\circ/2$ or $180^\circ/3$ or $180^\circ/4$.
3. Motor according to Claim 1 or 2, characterized in that the stator (2) has, viewed in cross-section, along a right-angled cross-sectional plane (A-A) with respect to the axis (x-x) of the rotor, one dimension substantially smaller than the other one; the arcs of a circumference inside which the slots (4) are arranged being situated on opposite sides with respect to a plane (A-A) passing through the axis (x-x) of the

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rotor and parallel to the smaller dimension of the stator.

4. Motor according to any one of the preceding claims, characterized in that the arcs of a circumference inside which the slots (4) are arranged are situated on opposite sides with respect to a plane (A-A) passing through the axis (x-x) of the rotor; the thickness of the stator (2), considered in a radial direction with respect to the axis (x-x) of the rotor, being minimal in two zones of the stator situated in the vicinity of said plane (A-A).
5. Motor according to any one of the preceding claims, characterized in that the stator (2) has, viewed in cross-section, along a right-angled cross-sectional plane with respect to the axis (x-x) of the rotor, a substantially rectangular shape.
6. Motor according to Claim 5, characterized in that the short side of the rectangular section of the stator (2) has a length slightly greater than the external diameter of an air gap (6) separating the rotor and the stator.

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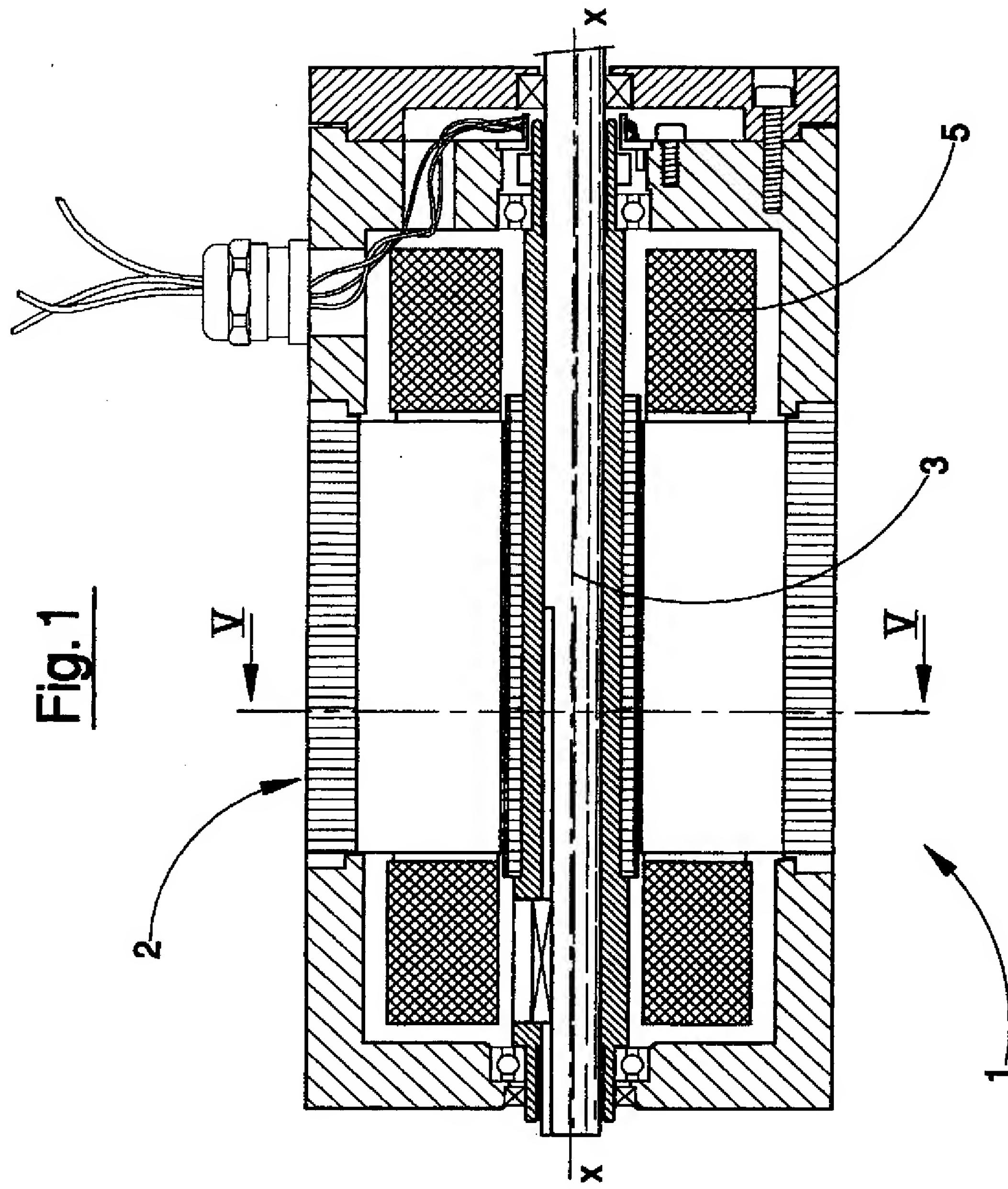
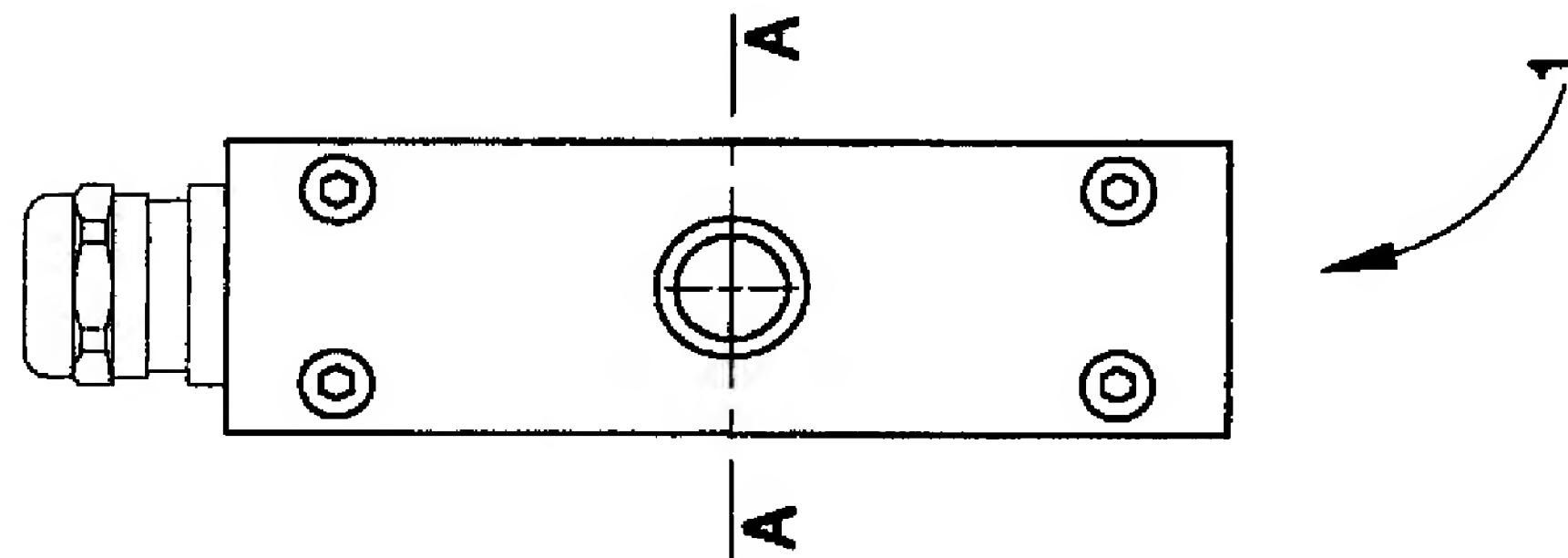


Fig. 1

Fig. 2



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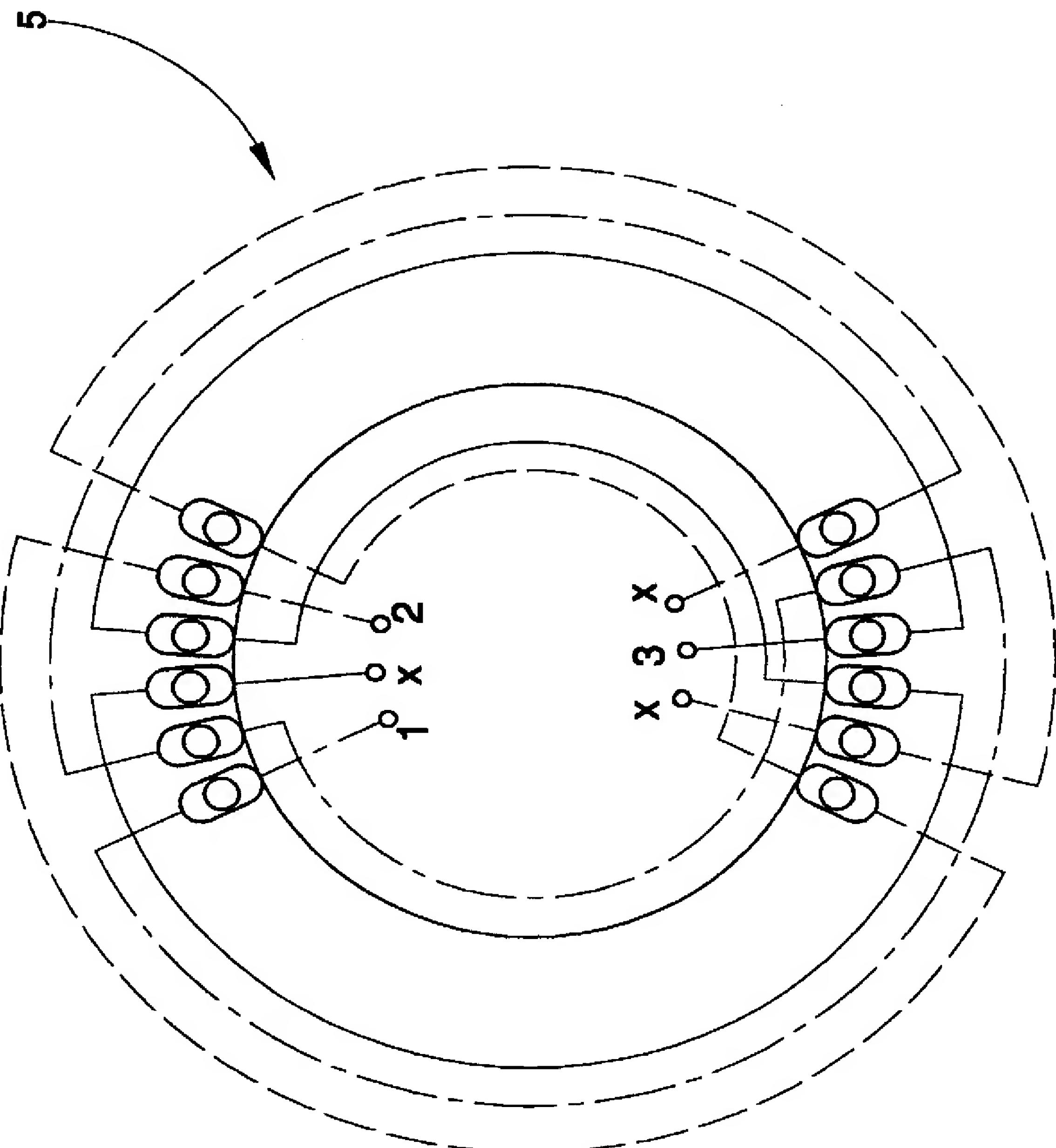
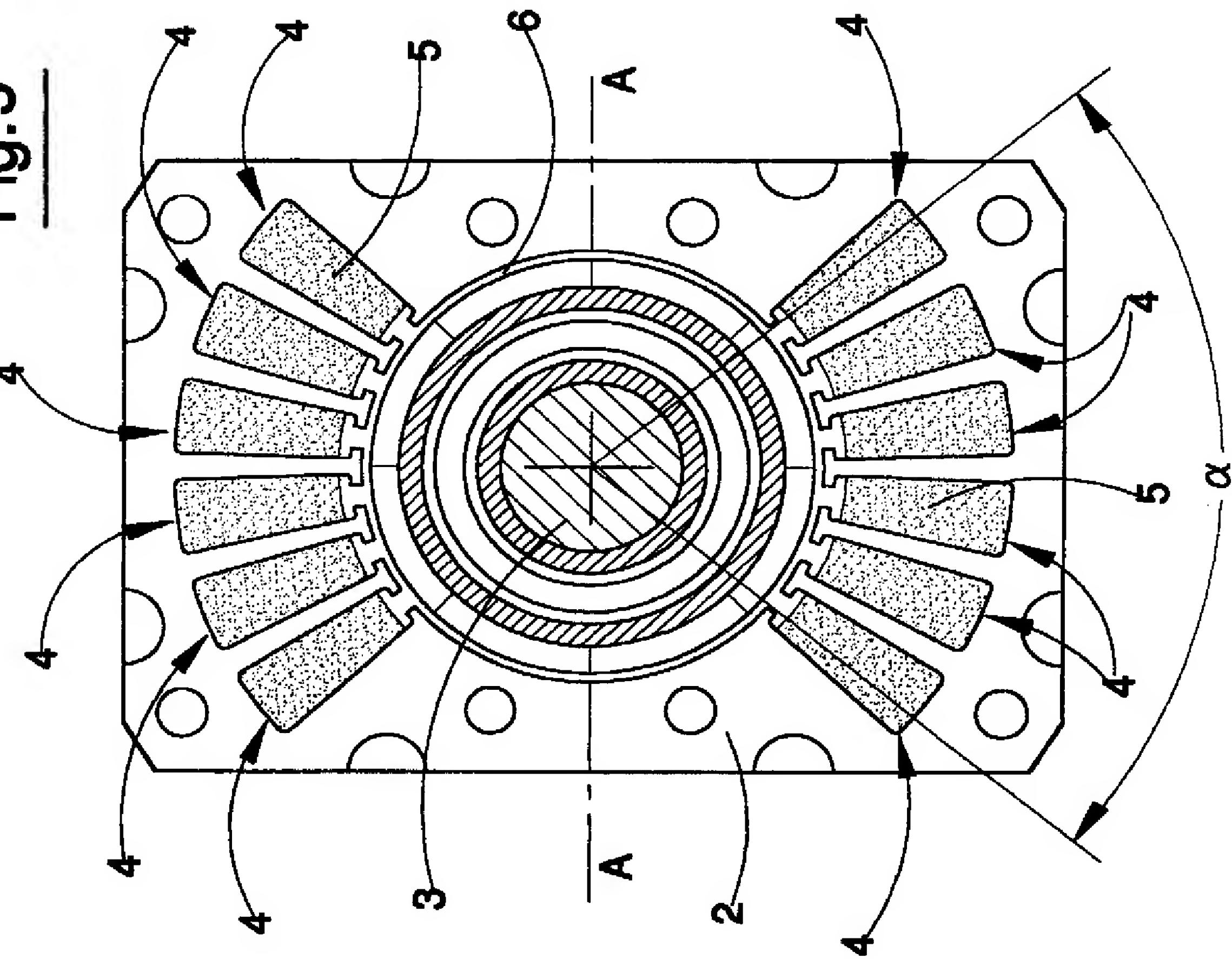
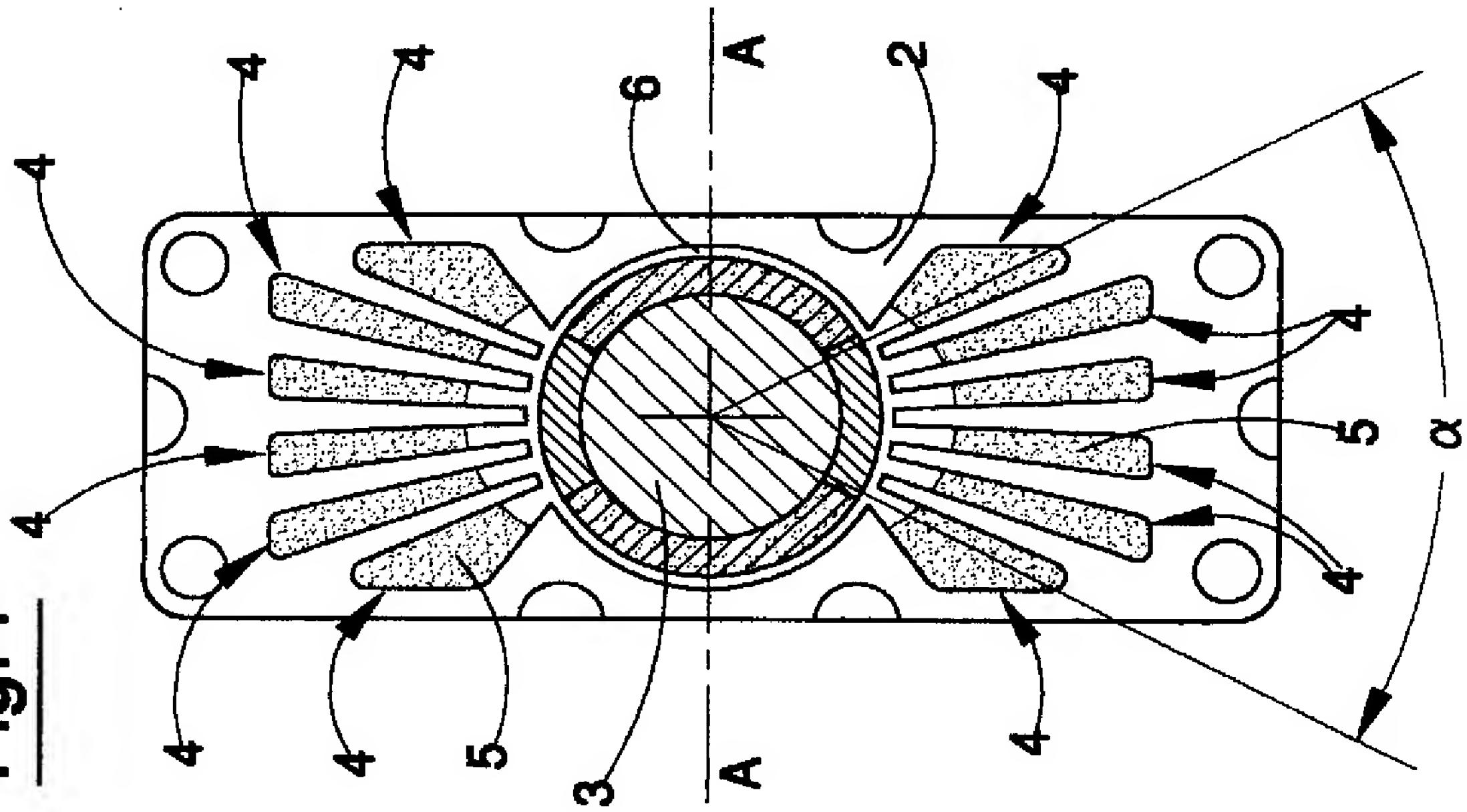


Fig. 3 |

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Fig. 5**Fig. 4**

INTERNATIONAL SEARCH REPORT

International Application No

PCT/IT 00/00074

A. CLASSIFICATION OF SUBJECT MATTER

IPC 7 H02K1/16

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C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	CH 433 503 A (GIORGIO BIGLINO ET AL) 15 April 1967 (1967-04-15) ----	
A	US 2 830 209 A (HANS FLECKENSTEIN) 8 April 1958 (1958-04-08) ----	
A	DE 11 86 547 B (WILHELM BREITLING) 4 February 1965 (1965-02-04) ----	
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Patent document cited in search report	Publication date	Patent family member(s)		Publication date
CH 433503	A	NONE		
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